

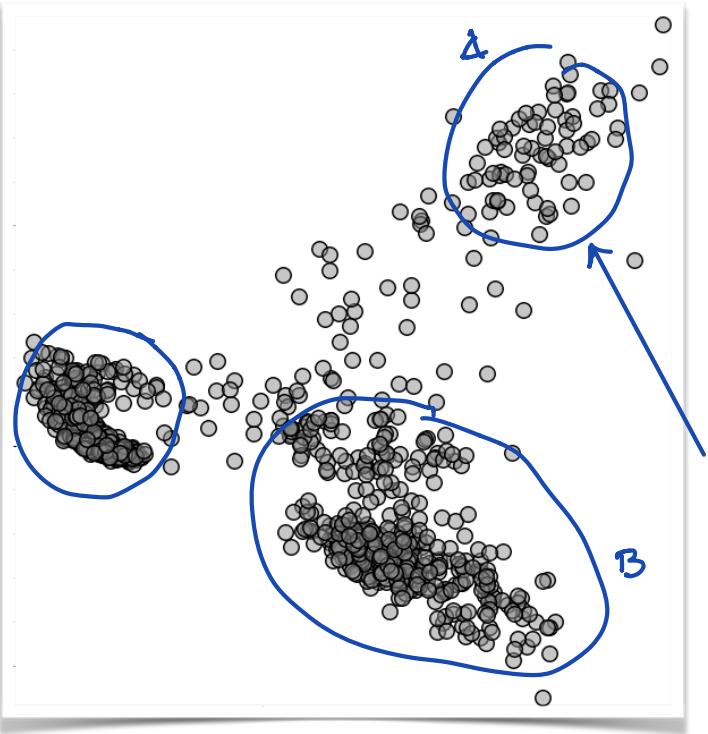
Unsupervised Learning

Machine Learning for Data Science 1

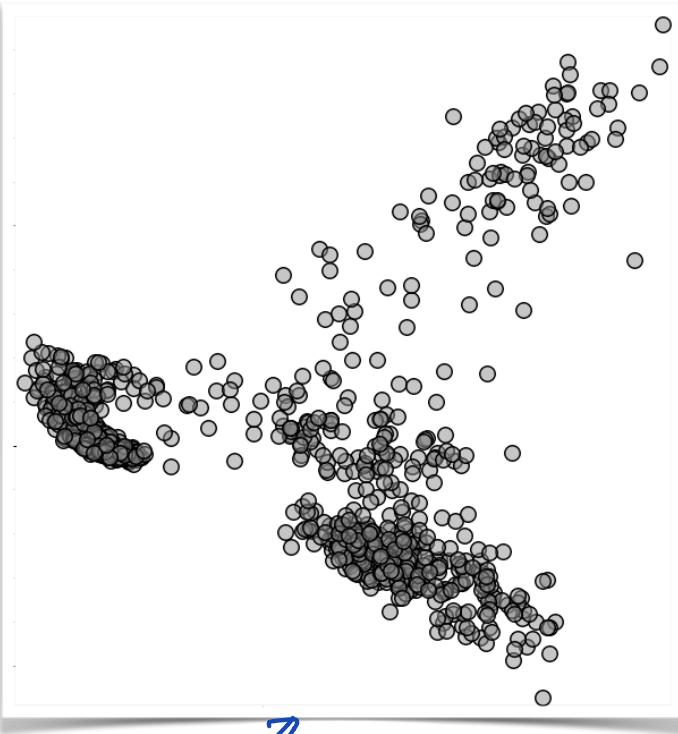
Draws inferences from data without known labels and responses.
Wikipedia: type of ML to find previously undetected patterns
In a data with no preexisting labels and
without external human supervisor.
not true

Interpretation is central
and we is free from guidance
or free approach

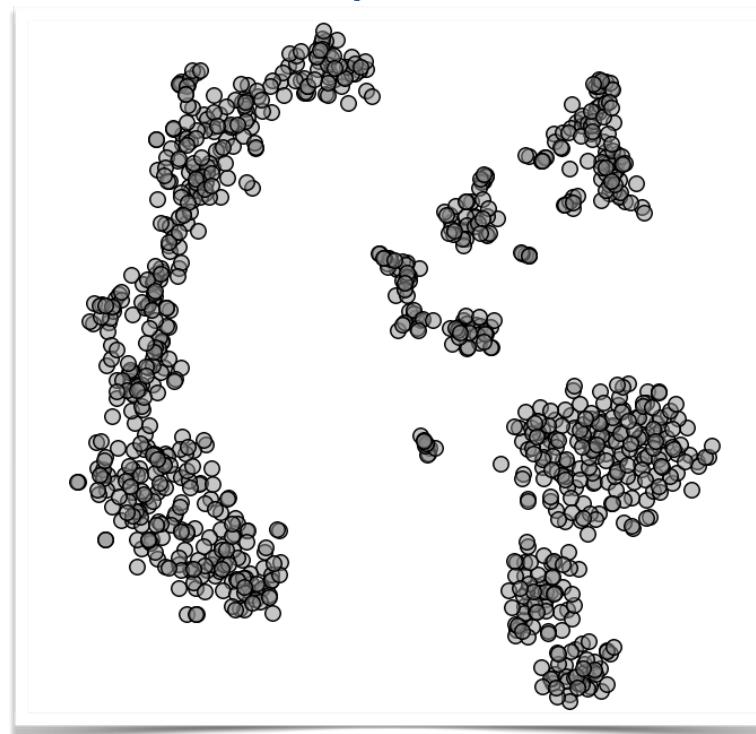
choice of parameters
approach
over fitting
overinterpretation



original space of >1000 features
principal component analysis
how we 7 groups do we see
interpretation
is the data that I have enough
variables.

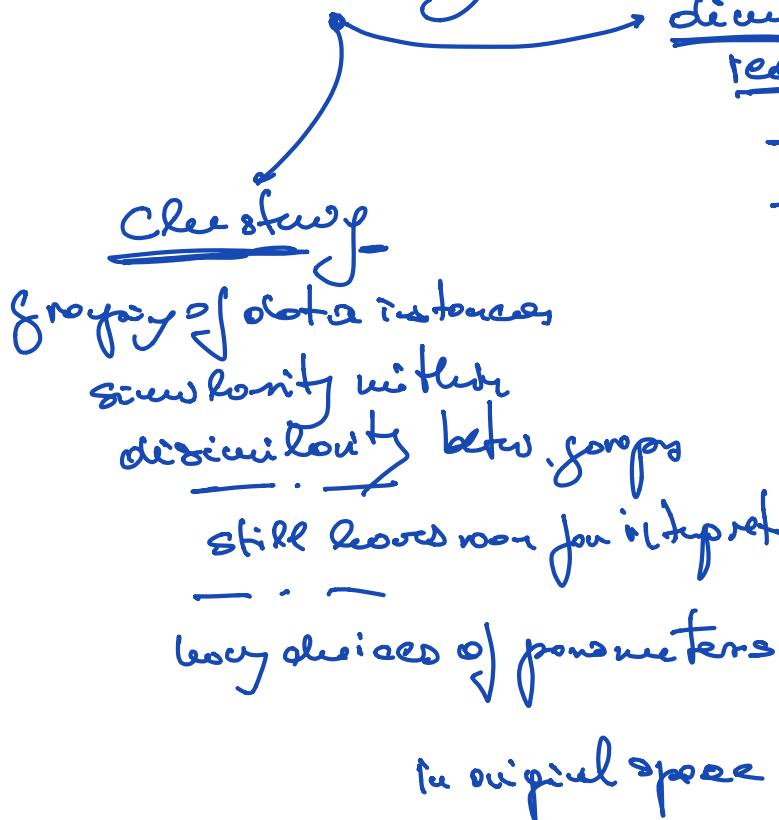


PCA



t-SNE

principled approaches to unsupervised learning

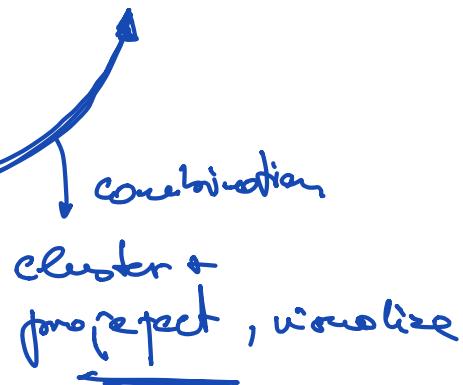


dimensionality reduction

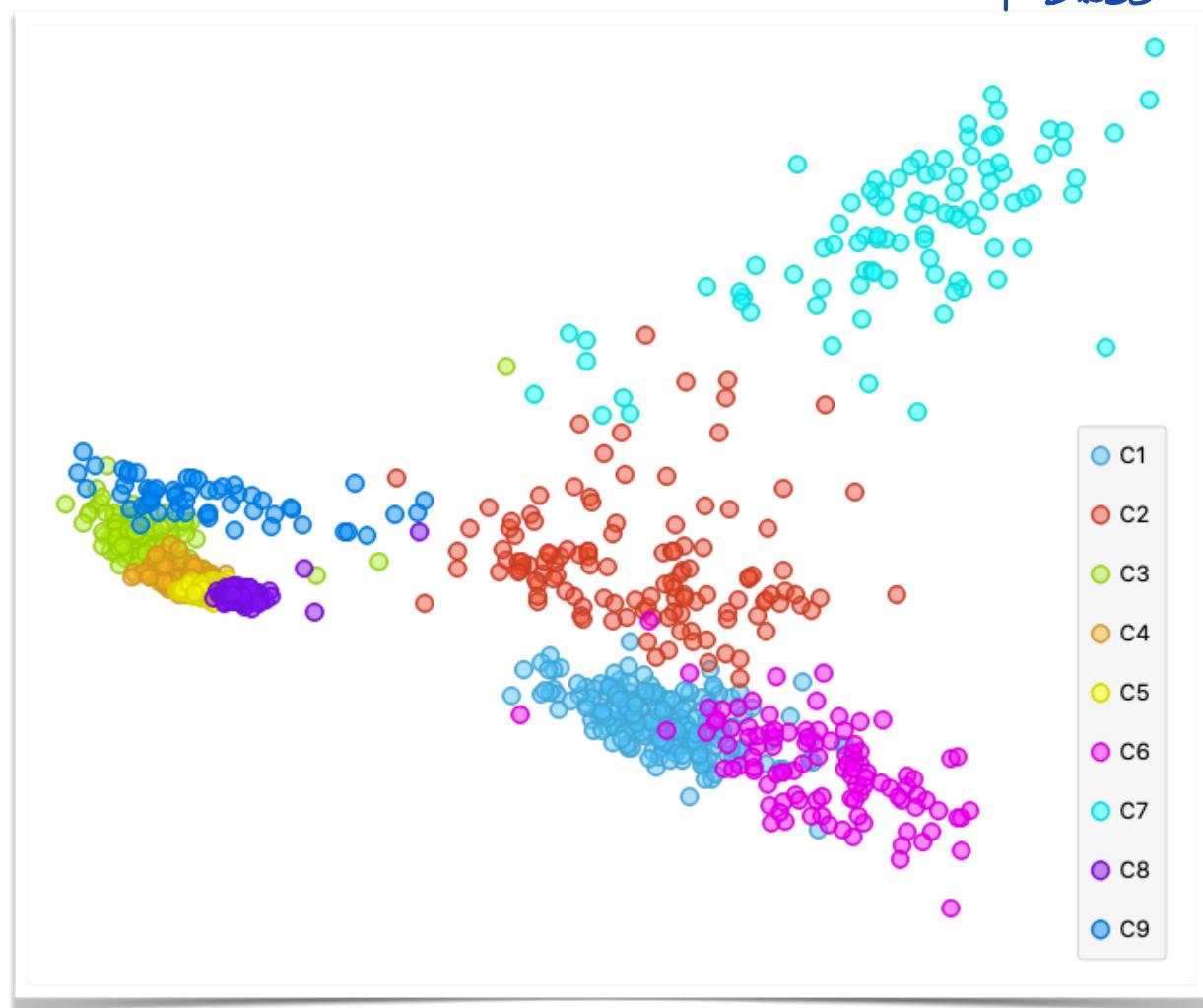
- projections (change of coord. sys)
- embedding (new latent space)

2D, 1D

fairness

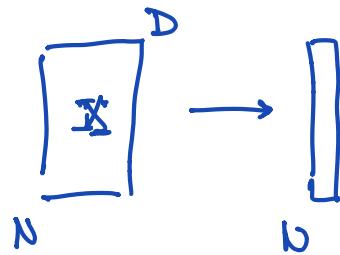


PCA , S1000



Principal Component Analysis

dimensionality reduction



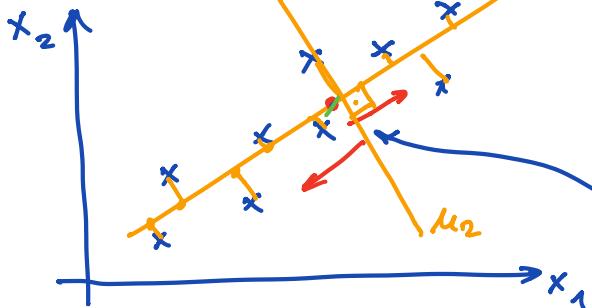
$D \gg d$

$d = 2 \leftarrow$ visualization

$d = 1 \leftarrow$ sense of time
projection
development

→ maximize the

variance of projections



μ_1 ← direction of projection

$$\mu_1^T \mu_1 = 1$$

or unit vector

$$x \in \mathbb{X}$$

$$\mu_1^T x \in \mathbb{R}$$

$$\mu_1^T \bar{x}, \quad \bar{x} = \frac{1}{m} \sum_{i=1}^m x_i$$

We are looking for μ_1 so that projected state points are maximally dispersed

$$\frac{1}{N} \sum_{i=1}^N (\mu_1^T x_i - \mu_1^T \bar{x})^2 = \underline{\text{Var}}(\mu_1^T X^T)$$

$$\begin{aligned} \text{Var}(\mu_1^T X^T) &= \frac{1}{N} \sum \left(\underbrace{\mu_1^T x_i}_{\substack{(\mu_1^T x_i)^T = x_i^T \mu_1^T}} \underbrace{\mu_1^T x_i}_{\substack{= x_i^T \mu_1^T}} - 2 \underbrace{\mu_1^T x_i}_{\substack{= x_i^T \mu_1^T}} \underbrace{\mu_1^T \bar{x}}_{\substack{= \bar{x}^T \mu_1^T}} + \underbrace{\mu_1^T \bar{x}}_{\substack{= \bar{x}^T \mu_1^T}} \underbrace{\mu_1^T \bar{x}}_{\substack{= \bar{x}^T \bar{x}}} \right) \\ &= \mu_1^T \left(\frac{1}{N} \sum \left(x_i^T x_i^T - 2 x_i^T \bar{x}^T + \bar{x}^T \bar{x}^T \right) \right) \mu_1 \\ &= \mu_1^T \left(\frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(x_i - \bar{x})^T \right) \mu_1 \end{aligned}$$

$$\sum_{i=1}^N x_i^j x_i^k$$

K_{xx}

covariance matrix

$$\sum_{i=1}^N x_i^j y_i^k$$

K_{xy}

$$\sum_{i=1}^N x_i^j x_i^k$$

K_{yy}

$$\text{Var}(\underline{u}_1^T X^T) = \underline{u}_1^T K \underline{u}_1 \rightarrow \begin{array}{l} \text{For PCA} \\ \text{maximize} \\ \text{constraint: } \underline{u}_1^T \underline{u}_1 = 1 \end{array}$$

Lagrange:

$$f(\underline{u}_1) = \underline{u}_1^T K \underline{u}_1 + \lambda_1 (1 - \underline{u}_1^T \underline{u}_1)$$

$$\nabla f(\underline{u}_1) = \underline{K} \underline{u}_1 - \lambda_1 \underline{u}_1 = 0$$

$$\underline{K} \underline{u}_1 = \underline{\lambda}_1 \underline{u}_1$$

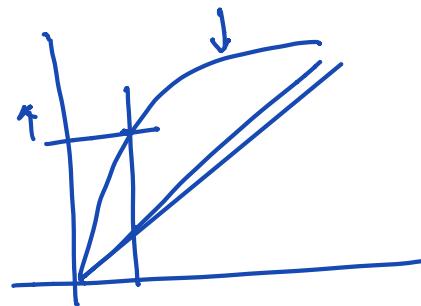
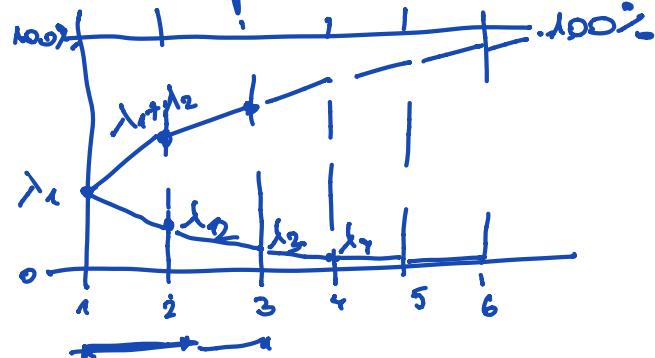
↓ ↓
eigenvector eigenvalue

$$\underline{u}_1^T K \underline{u}_1 = \text{Var}(\underline{u}_1^T X^T) = \underline{u}_1^T \underline{\lambda}_1 \underline{u}_1 = \underline{\lambda}_1$$

PCA : 1st component = \underline{u}_1 of K , λ_1

Scree diagram

variance explained



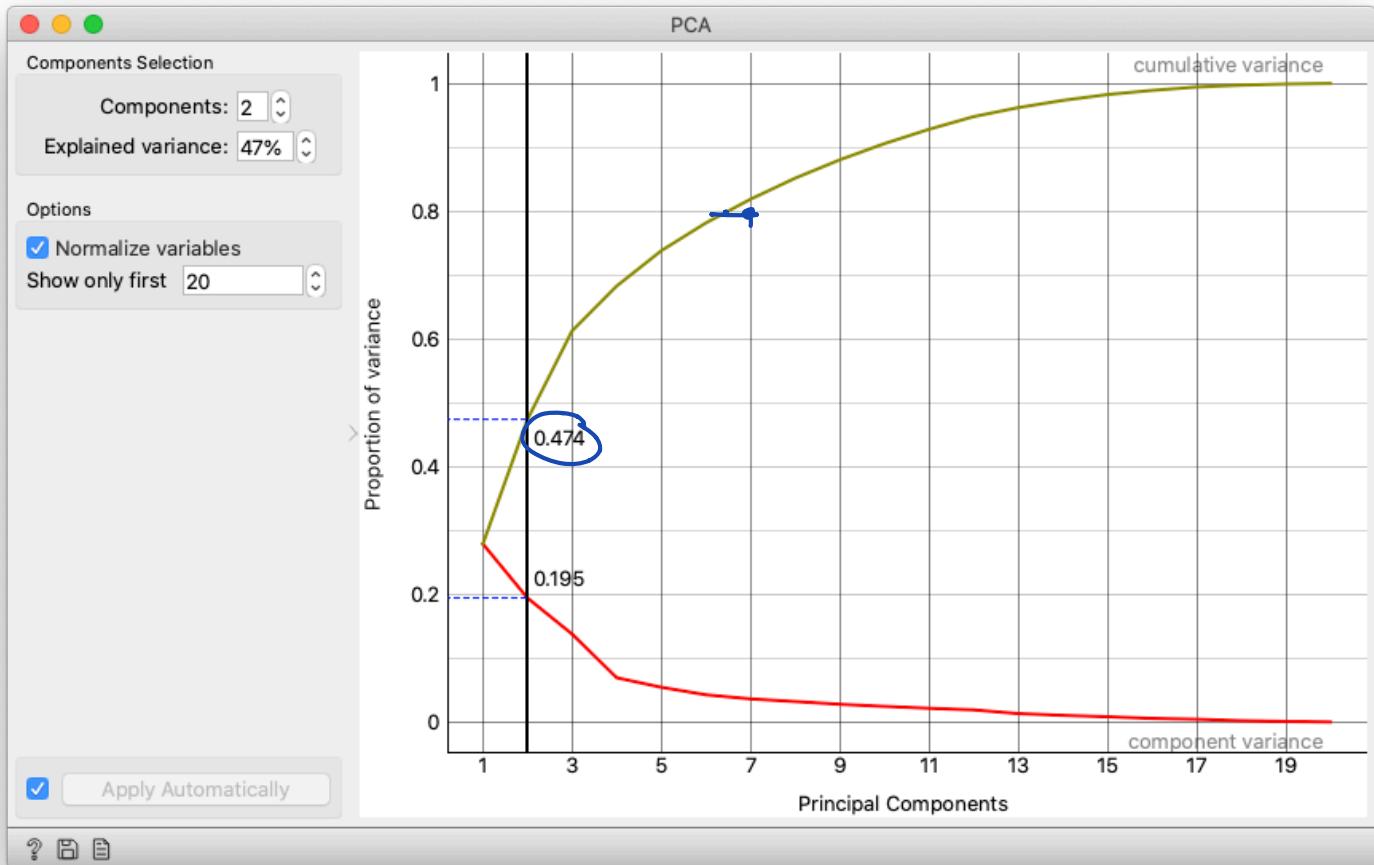
80%, 90%

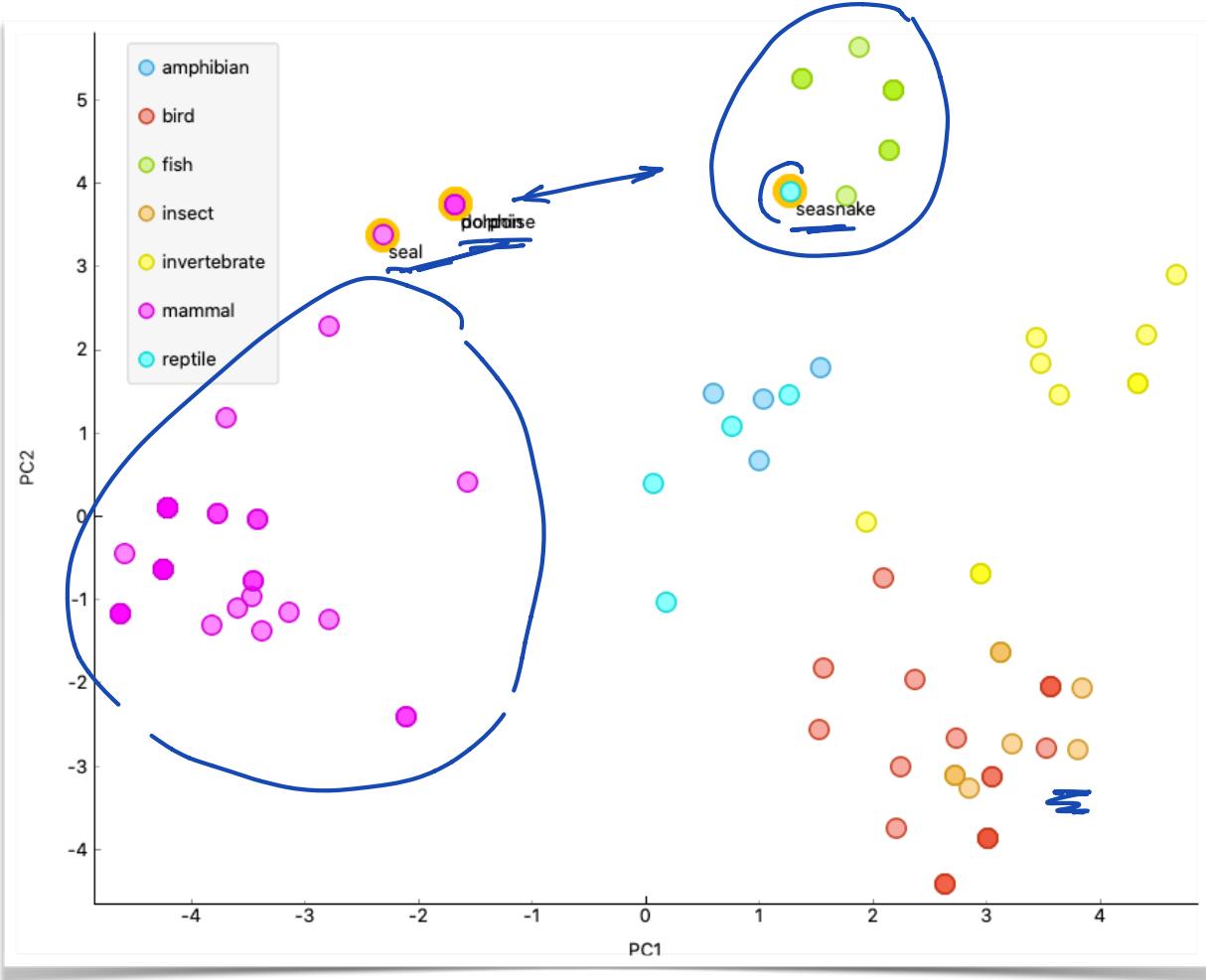
- how many dimensions?

- one to find ~~&~~ 2 dim. "in front of each"

- power needed

- gram-schmidt orthog.





Singular Value Decomposition

		Users			SVD				
		Asha Is parity	Titanic	Ben Solit met Hong	Matrix	Principle.			
Women	Tony	1	2	1	0	0	-	1	0
	Eve	5	6	7	0	0	-	1	0
	Johann	2	3	1	0	0	-	1	0
	Tom	1	2	1	1	0	-	7	0
men	Trix	0	0	0	5	7	-	0	1
	Bible	6	0	0	4	2	-	0	1

$$\rightarrow \begin{array}{ccccc} & 1 & 1 & 1 & 0 0 \\ & \underline{-} & & & \\ 0 & 0 & 0 & & 1 1 \\ & \underline{-} & & & \end{array}$$

$\rightarrow S$ truncated decomposition

$$\underline{\underline{X}} = \underline{\underline{U}} \sum \underline{\underline{V}}^T$$

↓ ↓ ↓
 $N \times D$ $N \times R$ $R \times D$

$\underline{\underline{U}}^T \cdot \underline{\underline{J}} = \underline{\underline{I}}$

$\underline{\underline{V}}^T \cdot \underline{\underline{J}} = \underline{\underline{I}}$

cc f, rows

$$\hat{\underline{\underline{X}}} = \underline{\underline{U}} \begin{bmatrix} \text{shaded} & 0 & \dots \\ 0 & \ddots & & 0 \\ \vdots & & \ddots & 0 \\ 0 & & & \text{shaded} \end{bmatrix} \underline{\underline{V}}^T$$

men, cols

$$\underline{\underline{X}} = \underline{\underline{U}} \sum \underline{\underline{V}}^T$$

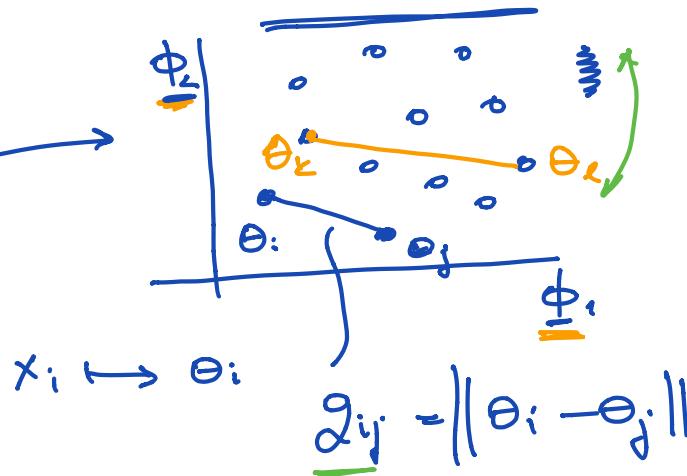
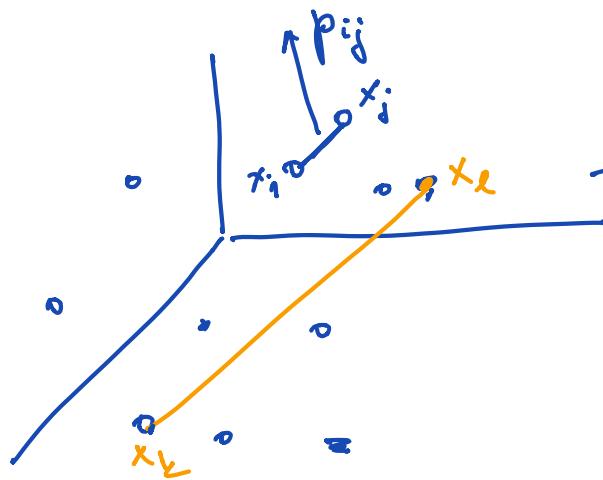
$$\underline{\underline{X}}^T = \underline{\underline{V}} \sum \underline{\underline{U}}^T = \underline{\underline{V}} \sum \underline{\underline{U}}^T$$

$$\underline{\underline{X}}^T \underline{\underline{X}} = \underline{\underline{V}} \sum \underline{\underline{U}}^T \underbrace{\underline{\underline{U}} \sum \underline{\underline{V}}^T}_{\underline{\underline{I}}} = \underline{\underline{V}} \sum^2 \underline{\underline{V}}^T$$

$$\underline{\underline{X}}^T \underline{\underline{X}} \circledcirc = \underline{\underline{V}} \sum^2 \underline{\underline{V}}^T \underline{\underline{V}} = \underline{\underline{V}} \circledcirc$$

PCA : projection

embedding : Multidimensional Scaling MDS



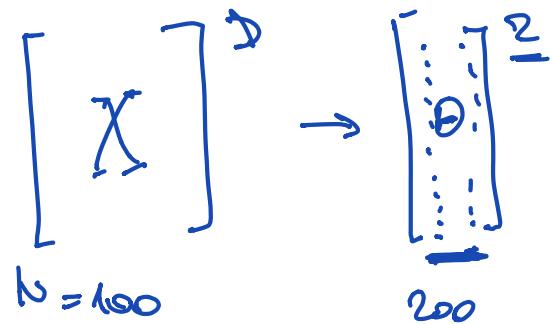
$$p_{ij} = \|x_i - x_j\|$$

any kind of distance

Preserve
distances!

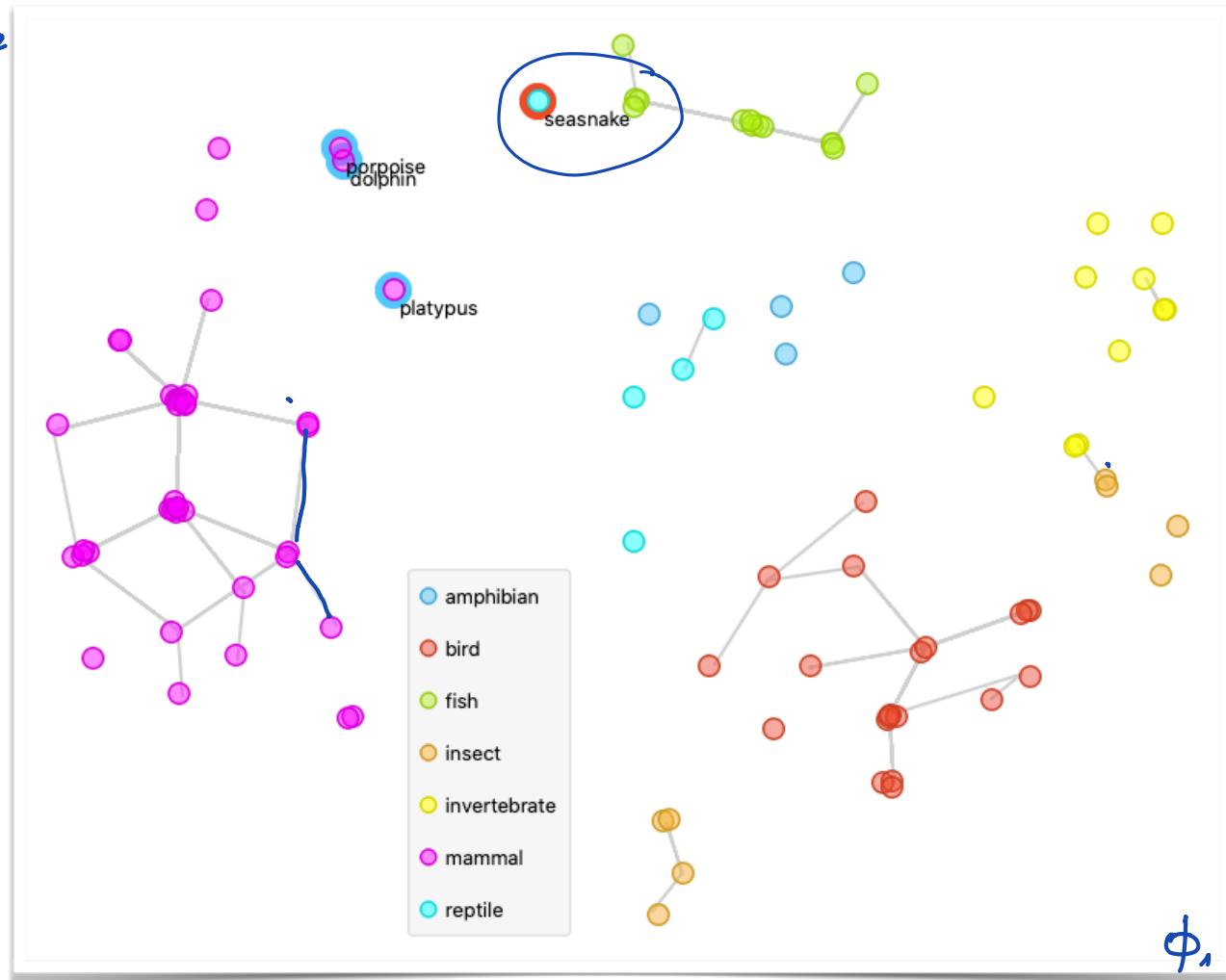
$$\hat{J}(\Theta) = \sum_{i \neq j}^N (p_{ij} - g_{ij})^2 : \text{minimize}$$





$$\begin{aligned}
 \frac{\partial J(\theta)}{\partial \phi_i^{(j)}} &= \sum_{i \neq j} \frac{\partial J(\theta)}{\partial g_{ij}} \frac{\partial g_{ij}}{\partial \phi_i^{(j)}} \\
 &= 2 \sum_{i \neq j} \frac{(g_{ij} - p_{ij})}{\text{error}} \frac{\phi_i^{(j)} - \phi_j^{(j)}}{g_{ij}} \quad | \text{ direction of change}
 \end{aligned}$$

Solutions, majorisation, STACOF
 \downarrow speedup
 convergence

ϕ_2 ϕ_1 

Stochastic Neighbor Embedding - SNE

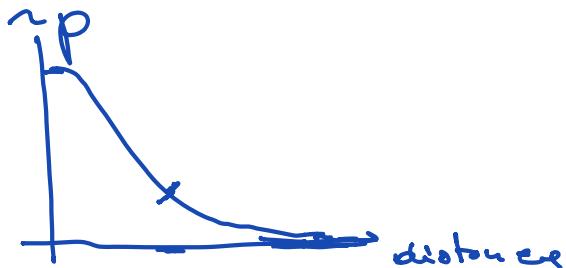
2002 Hinton & Roweis

2008 vander Maaten t-SNE

Idea

distinguishable close to each other
in the original space

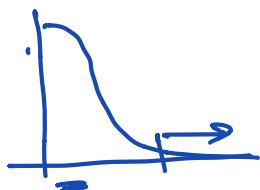
Should be close in embedding



$$p_{j|i} = \frac{e^{-\frac{\|x_i - x_j\|^2}{2\sigma_i^2}}}{\sum_{k \neq i} e^{-\frac{\|x_i - x_k\|^2}{2\sigma_i^2}}}$$

perplexity

original space



latent space Φ_2

$$q_{j|i} = \frac{e^{-\|\phi_i - \phi_j\|^2}}{\sum_{k \neq i} e^{-\|\phi_i - \phi_k\|^2}}$$

SNE

$$\underline{J(\theta)} = \sum_i \sum_j p_{ii} \log \frac{p_{ii}}{q_{j|i}} =$$

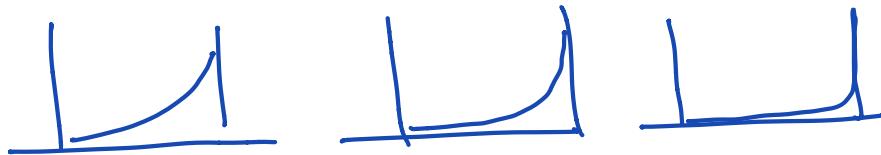
$$= \sum_i \underline{\text{KL}(P_i || Q_i)}$$

$$\frac{\partial J}{\partial \theta^{(i)}} = 2 \sum_j \left(q_{j|i} - p_{ii} + p_{ij} - q_{i|j} \right) \left(\underline{\theta^{(i)}} - \underline{\theta^{(j)}} \right)$$

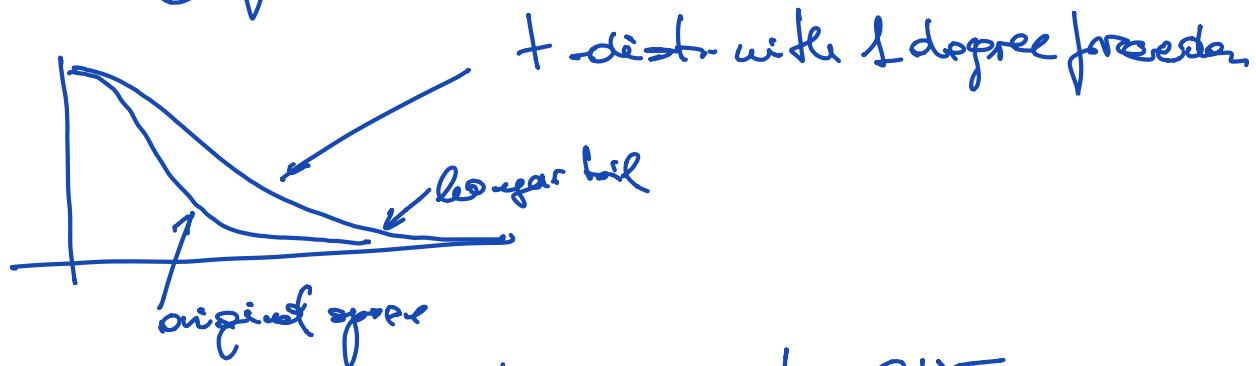
SNE

one dimension
space
1000 feet

two dimensions
space
2



The crowding problem

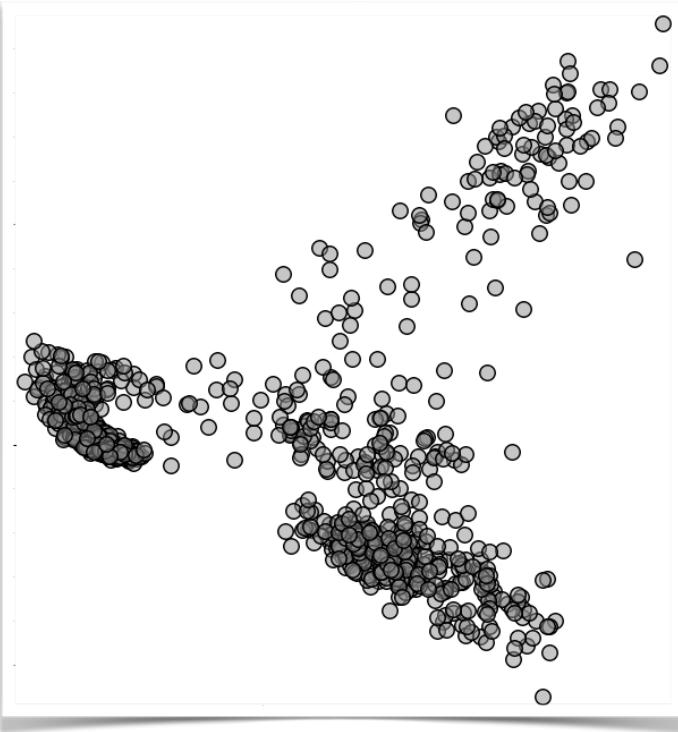


$$g_{ij} = \frac{(1 + \|x_i - x_j\|^2)^{-1}}{\sum_{k \neq i} (1 + \|x_i - x_k\|^2)^{-1}}$$

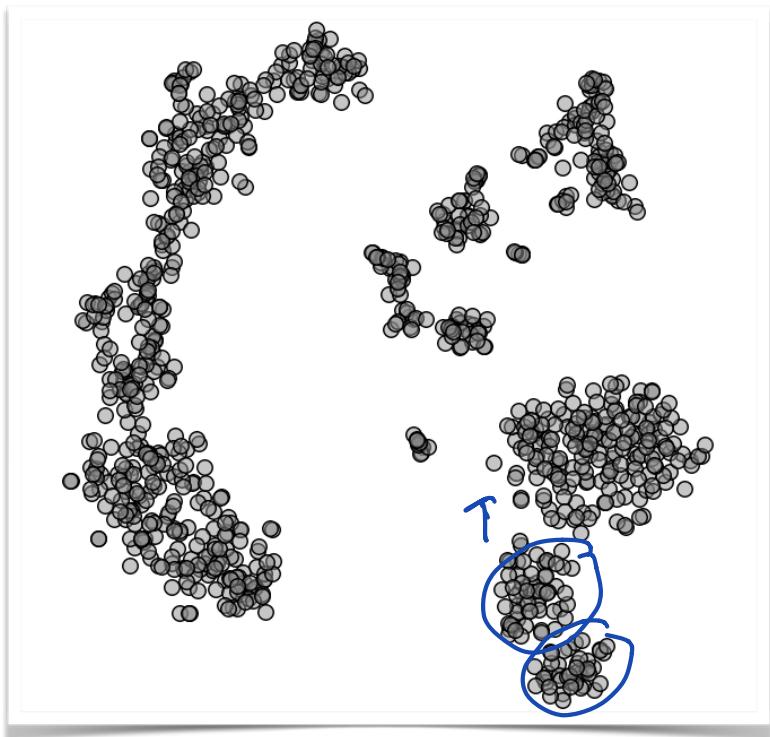
t-SNE

$$\frac{\partial^3}{\partial \theta^{(n)}} = 4 \sum \underbrace{(\hat{p}_{ij} - q_{ij})}_{\text{error}} \underbrace{(\phi_i - \phi_j)}_{\text{direction}} \underbrace{\left(1 + \|\phi_i - \phi_j\|^2\right)^{-1}}_{\text{weight}}$$

PCA



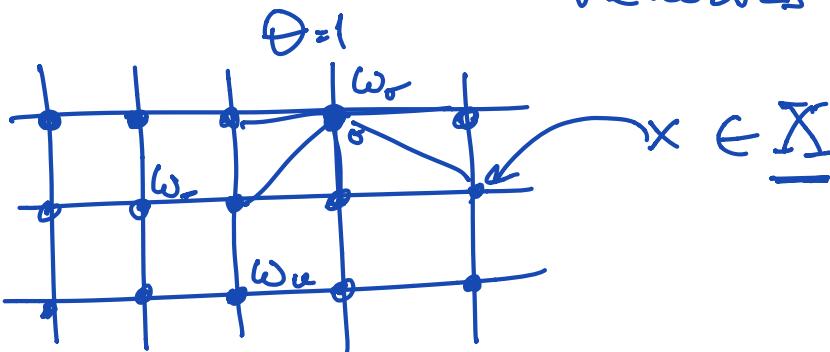
t-SNE



Self-Organizing Tops

Kohonen maps

networks



w_0 : prototype

1. Initialize w_0
2. randomly pick $x \in \underline{X}$
3. find node w_u
↳ arg min $\|x - w_i\|$, we place x in node w_u
4. $w_0 \leftarrow w_0 + \Theta_{(e, u)} \cdot \alpha (w_0 - x)$
5. if stopping condition met
 go to 2

